APURVAKUMAR JANI

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Summary

• Self-driven professional with 4+ years of experience in Mechatronics and Design. Passionate about making career in robotics and automation industry. Looking for full time opportunities.

Education and Training

09/2020 Buffalo	 Master of Science (Thesis) in Mechanical Engineering (Major in Mechatronics and Control) University at Buffalo, SUNY 3.9 GPA Coursework: Mechatronics, Advanced Control Systems, Manufacturing Automation, Continuous Control System, System Analysis, Design and Optimization, Heuristic Optimization, Human Robot Interaction Teaching Aid/Grader: Digital Control Systems, Manufacturing automation, Design project
06/2016	Bachelor of Science in Mechanical Engineering Technology

Skills

India

- Domain skills: RoboticControl systems, Mechatronics design, Optimization, GD & T, DFMEA
- Programming Languages & Software: Python, C++, C#, MATLAB, Simulink, LabView, PLC ladder
- Operating Systems: Linux, ROS, MAVROS
- Embedded Protocols: CAN, I2C, UART, SPI, Bluetooth
- CAD & Product Management : Solidworks, CATIA V5 V6, Siemens Team enter, Enovia PLM, Ansys, PTC Creo

Experience

12/2018 - Current
HILS Lab, University
at Buffalo
Buffalo, NY

Robotics Researcher

MS University, Vadodara

- Developed robotics control framework using ROS, Python and C++ for robotic arm
- Designed modular version of on variable stiffness magnetic gripper (Gripper patented by HILS lab).
- Implemented **real-time stiffness control** of fingers via Touch display and developed GUI integrated with Raspberry pi
- Collecting and **analysing sensor data** for experiments
- Building **3D printed** prototypes
- Educated undergraduate students on laboratory protocols and activities.
- Supported principal investigators during research into Human Swarm Interaction.

07/2016 - 07/2018 TATA Technologies

Design R & D Engineer

- Designed **electro-mechanical parts** of vehicle and released drawings for the supplier.
- Ensured integration of vehicle by establishing communication between cross functional teams.
- Solved part failure related issues using 8D & DFMEA tools.
- Recommended design modifications to eliminate component and system malfunctions.
- Monitored design processes from conceptual phase through construction.
- Provided technical support at the client location
- Managed 3 junior diploma professionals

Publications

- Hemanth Manjunatha, Joseph Distefano, Apurv Jani, Ehsan Esfahani, Souma Chowdhury, Payam Ghassemi, '*Using Physiological Measurements to Analyze the Tactical Decisions in Human Swarm Teams*', SMC- 2020 (Paper accepted)
- Thesis, Interactive Shape Control of Swarm of Mobile Robots using Geographic Information System (GIS) based Shape Model, University at Buffalo, SUNY, 2020

Relevant Projects

Modular design and real time grasp control for variable stiffness end-effector

- Conceptualized modularity of gripper for making it commercially ready
- Implemented real-time stiffness control of fingers via **Touch display (HMI)** integrated with Raspberry pi
- Schunk LWA4P manipulator used for experiments. C++ and ROS are used to develop control framework

Product shape detection using vision sensor

- Implemented product shape detection for conveyor belt application using Vision sensor
- OpenCV is used for image processing and V-rep is used for simulation

Servo Motor Parameter Estimation & control by interfacing hardware with LabVIEW Software

- Interfaced QUANSER SRV02 series rotary servo plant to computer via LABVIEW software
- Designed and tuned of PID controller circuit for motor and parameter estimation

Nonlinear control of 2 link manipulator using Disturbance Observer

- Developed of nonlinear model of plant using Simulink
- Control Performance improved with the addition of Disturbance observer

Certification

SIEMENS Basics of PLC

Activities

Board of Directors, Graduate Student Association UB

• Organized social gatherings for graduate students and conveyed student concerns to upper management Led cleanliness campaign in suburban areas of Pune, India